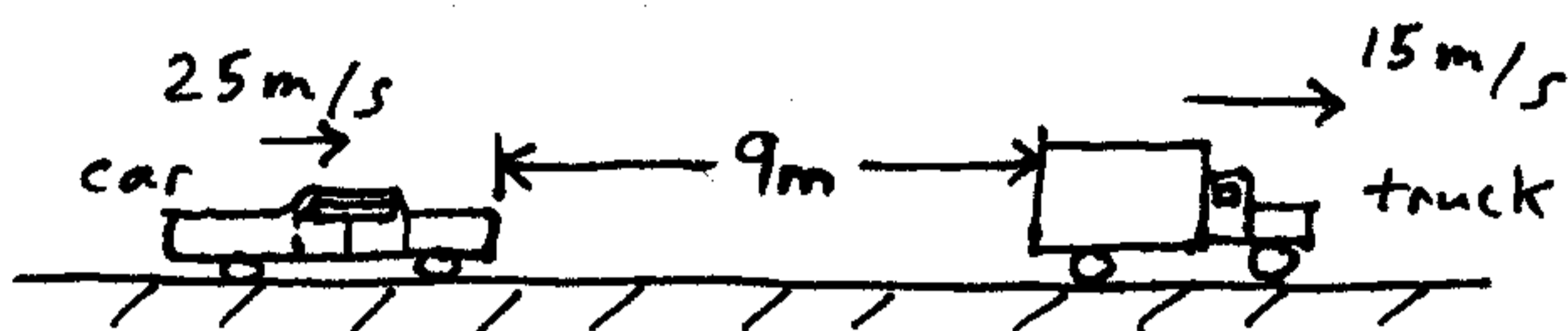


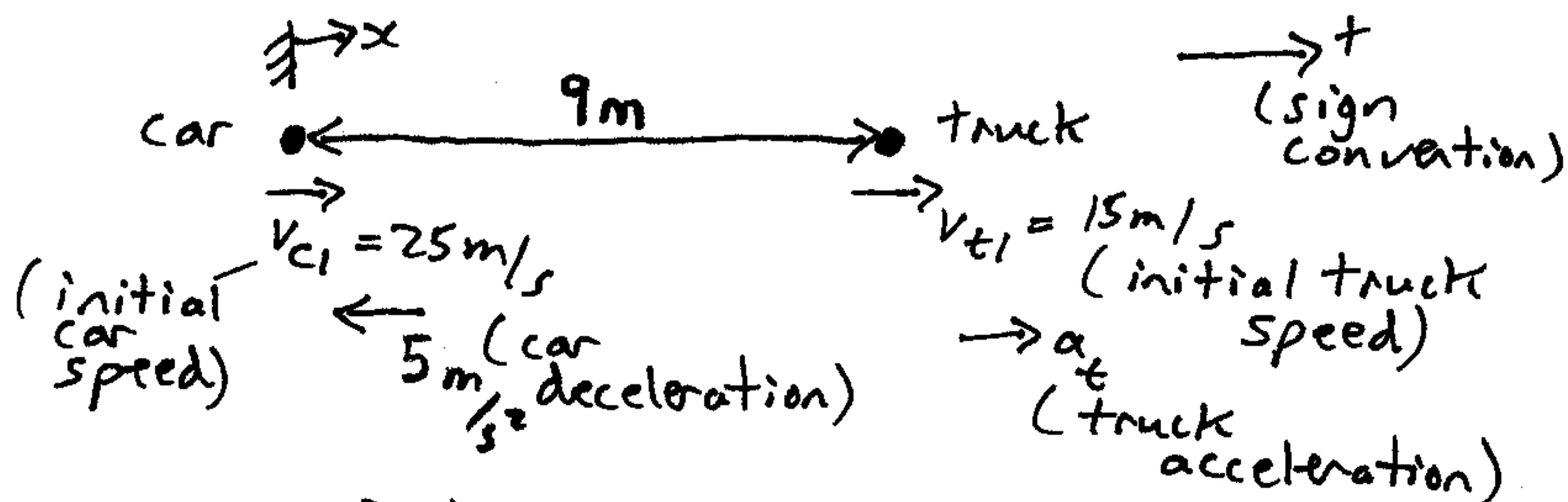
This is a 1-D problem involving constant acceleration.



A distracted driver is cruising at 25 m/s when he suddenly notices a truck directly ahead moving at 15 m/s, in the same direction. At the instant he brakes, the distance between the front of the car and the back of the truck is 9 m. The car decelerates at 5 m/s^2 , and one second after the driver of the car applies the brakes, the truck driver notices the car behind and starts accelerating at a_t . What is the minimum value of a_t in order to avoid a collision?

Solution:

Set up a coordinate frame with origin at the car location at the instant the brakes are applied.



The position of the car is:

$$x_c = v_{c1}t - \frac{1}{2}(5)t^2, \text{ where } t \text{ is the time from when the brakes are applied.}$$

For $0 \leq t \leq 1$, the position of the truck is:

$$x_t = 9 + v_{t1} t \quad (\text{truck driver doesn't notice car behind him and continues at same speed})$$

For $t > 1$, the position of the truck is:

$$x_t = \underbrace{9 + v_{t1}(1)}_{\text{position of truck at instant truck driver starts accelerating}} + \underbrace{v_{t1}(t-1) + \frac{1}{2}a_t(t-1)^2}_{\text{Note that we must use } (t-1), \text{ and not } t, \text{ since truck acceleration starts at a time that is offset by 2 second from when the car starts braking}}$$

Simplify:

$$x_t = 9 + v_{t1} t + \frac{1}{2} a_t (t-1)^2$$

Check the separation distance between car and truck at $t = 1$ second:

$$x_t - x_c = 9 + 15(1) - (25(1) - \frac{1}{2}(5)(1)^2)$$

$$x_t - x_c = 1.5 \text{ m} \quad (\text{no collision - good - this means that the truck has the possibility to accelerate out of the way})$$

Now, for $t > 1$ second,

$$x_t - x_c = 9 + 15t + \frac{1}{2} a_t (t-1)^2 - (25t - \frac{1}{2}(5)t^2)$$

Simplify:

$$x_t - x_c = 9 - 10t + (\frac{1}{2} a_t + 2.5)t^2 - a_t t + \frac{1}{2} a_t$$

$$x_t - x_c = 9 + \frac{1}{2} a_t - (10 + a_t)t + (\frac{1}{2} a_t + 2.5)t^2$$

This is a quadratic equation and we can complete the square:

$$x_t - x_c = \left(\frac{1}{2}a_t + 2.5\right)t^2 - (10 + a_t)t + 9 + \frac{1}{2}a_t$$

$$x_t - x_c = \left(\frac{1}{2}a_t + 2.5\right)\left(t^2 - \frac{(10 + a_t)t}{\left(\frac{1}{2}a_t + 2.5\right)}\right) + 9 + \frac{1}{2}a_t$$

$$x_t - x_c = \left(\frac{1}{2}a_t + 2.5\right)\left(t^2 - \frac{(10 + a_t)t}{\left(\frac{1}{2}a_t + 2.5\right)} + \frac{(10 + a_t)^2}{4\left(\frac{1}{2}a_t + 2.5\right)^2} - \frac{(10 + a_t)^2}{4\left(\frac{1}{2}a_t + 2.5\right)^2}\right)$$

$$x_t - x_c = \left(\frac{1}{2}a_t + 2.5\right)\left(t - \frac{(10 + a_t)}{2\left(\frac{1}{2}a_t + 2.5\right)}\right)^2$$

$$- \frac{(10 + a_t)^2}{4\left(\frac{1}{2}a_t + 2.5\right)} + 9 + \frac{1}{2}a_t$$

The minimum value of a_t in order to avoid a collision corresponds to a minimum separation distance equal to zero (so that the car and truck are barely touching)

The above quadratic equation has a minimum value of zero when:

$$- \frac{(10 + a_t)^2}{4\left(\frac{1}{2}a_t + 2.5\right)} + 9 + \frac{1}{2}a_t = 0$$

Simplify, and the above equation becomes:

$$\frac{-(10 + a_t)^2 + (9 + \frac{1}{2}a_t)(2a_t + 10)}{4(\frac{1}{2}a_t + 2.5)} = 0$$

$$\Rightarrow \frac{-(a_t^2 + 20a_t + 100) + (18a_t + 90 + a_t^2 + 5a_t)}{4(\frac{1}{2}a_t + 2.5)} = 0$$

$$\Rightarrow \frac{3a_t - 10}{4(\frac{1}{2}a_t + 2.5)} = 0$$

$$\Rightarrow 3a_t - 10 = 0$$

$$a_t = \frac{10}{3} \text{ m/s}^2 \text{ (answer)}$$

This is the minimum truck acceleration to avoid a collision.