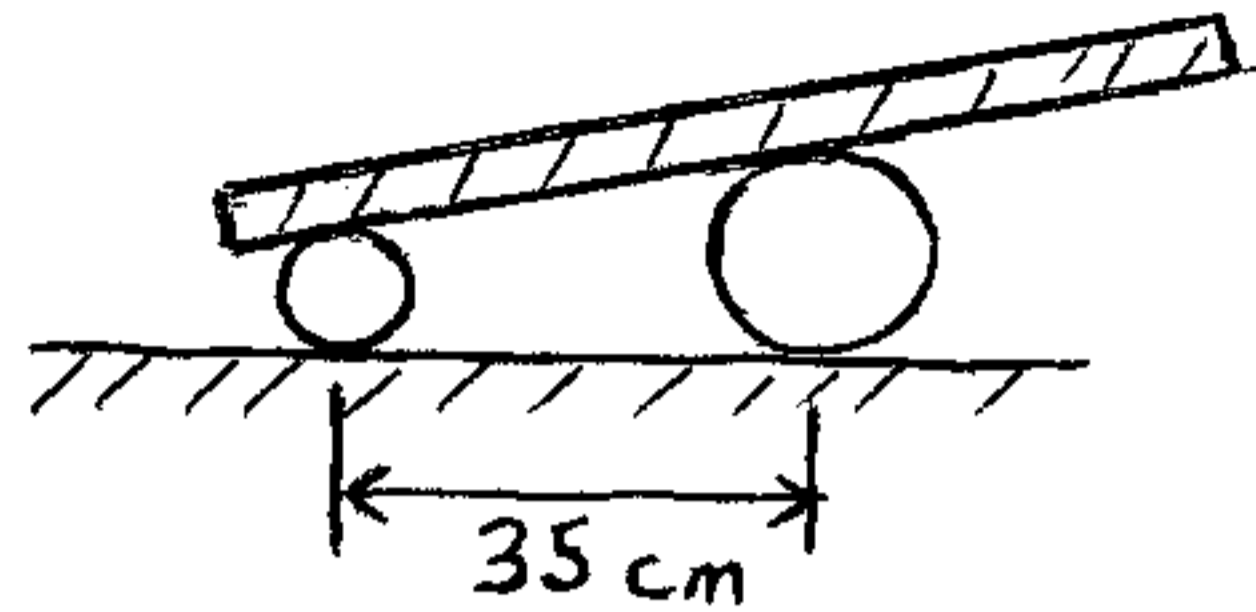
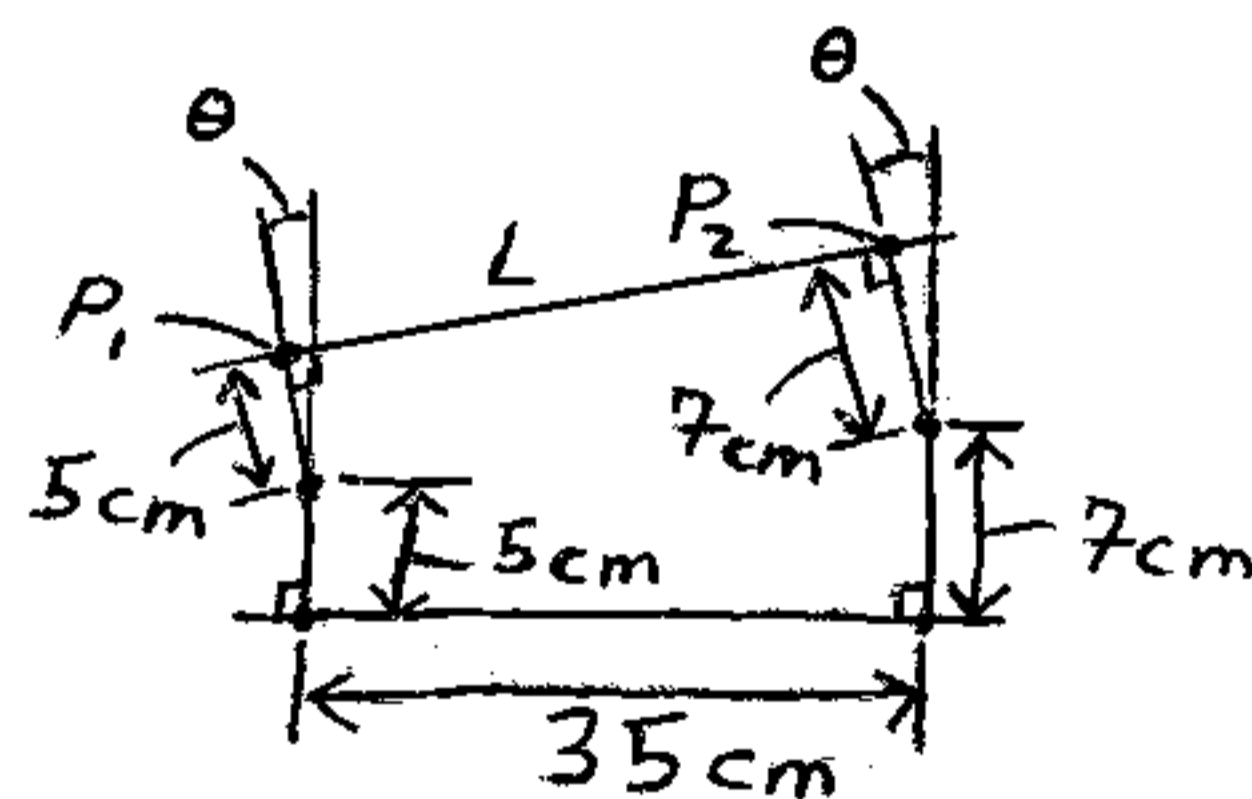
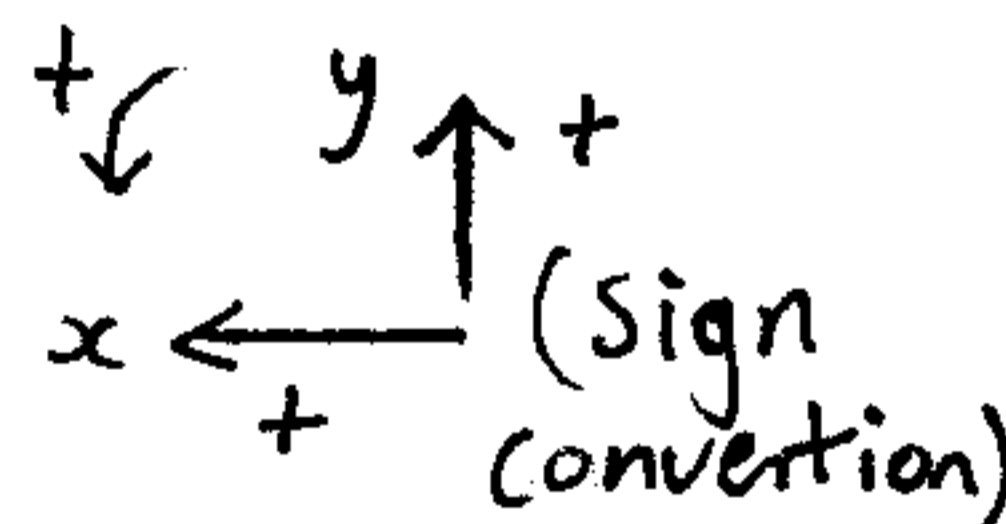


This is a problem involving conservation of energy.



A board is supported by two cylinders on a horizontal surface, as shown. The mass of the board is 13 kg, the mass and radius of the smaller cylinder is 5 kg and 5 cm, and the mass and radius of the larger cylinder is 10 kg and 7 cm. If the system is released from rest and there is no slipping anywhere, what is the velocity of the board after the cylinders have moved a distance of 30 cm? Assume the board stays in contact with the cylinders.

Solution:



The velocity of the center of mass of the smaller cylinder is:

$\vec{v}_{cm1} = \omega_1 R_1 \hat{e}$ (this is in the positive x-direction)
 - For rolling without slipping,
 where ω_1 , R_1 are the angular velocity and radius of smaller cylinder

P_1 is the contact point between board and smaller cylinder.
 P_2 is the contact point between board and larger cylinder.
 L is the distance between P_1 and P_2 .

The velocity of the center of mass of the larger cylinder is:

$$\vec{v}_{cm2} = \omega_2 R_2 \hat{i} \quad (\text{this is in the positive } x\text{-direction})$$

- for rolling without slipping, where ω_2, R_2 are the angular velocity and radius of larger cylinder

The velocity of point P_1 on the smaller cylinder is:

$$\vec{v}_{P_1} = \vec{v}_{cm1} + \omega_1 R_1 \cos\theta \hat{i} - \omega_1 R_1 \sin\theta \hat{j}$$

$$\Rightarrow \vec{v}_{P_1} = \omega_1 R_1 (1 + \cos\theta) \hat{i} - \omega_1 R_1 \sin\theta \hat{j} \quad (1)$$

Similarly, the velocity of Point P_2 on the larger cylinder is:

$$\vec{v}_{P_2} = \vec{v}_{cm2} + \omega_2 R_2 \cos\theta \hat{i} - \omega_2 R_2 \sin\theta \hat{j}$$

$$\Rightarrow \vec{v}_{P_2} = \omega_2 R_2 (1 + \cos\theta) \hat{i} - \omega_2 R_2 \sin\theta \hat{j} \quad (2)$$

The velocity of point P_1 on the board is:

$$\vec{v}_{P_1} = \vec{v}_{P_2} - \omega_b L \cos\theta \hat{j} - \omega_b L \sin\theta \hat{i} \quad (3)$$

ω
velocity of
point P_2 on the board

where ω_b is
the angular
velocity of
the board

Note:

$$\left(\omega_b = \frac{d\theta}{dt} \right)$$

Note:

\hat{i}, \hat{j}
are unit
vectors
pointing
along
positive
 x and y
directions,
respectively

Note that P_1 and P_2 do not move relative to the board because of the no slip condition. If there was slip there would need to be a relative velocity term added to equation (3).

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Substitute equations (1) and (2) into equation (3):

$$\begin{aligned} w_1 R_1 (1 + \cos \theta) \hat{i} - w_1 R_1 \sin \theta \hat{j} \\ = w_2 R_2 (1 + \cos \theta) \hat{i} - w_2 R_2 \sin \theta \hat{j} \\ - w_b L \cos \theta \hat{j} - w_b L \sin \theta \hat{i} \end{aligned}$$

By comparison:

$$(A) \quad w_1 R_1 (1 + \cos \theta) = w_2 R_2 (1 + \cos \theta) - w_b L \sin \theta$$

and

$$(B) \quad -w_1 R_1 \sin \theta = -w_2 R_2 \sin \theta - w_b L \cos \theta$$

$$(A) \times \sin \theta + (B) \times (1 + \cos \theta):$$

$$\Rightarrow 0 = -w_b L \sin^2 \theta - w_b L \cos \theta (1 + \cos \theta)$$

$$\Rightarrow 0 = -w_b L (1 + \cos \theta)$$

The only possible solution is $w_b = 0$, which then means that $w_1 R_1 = w_2 R_2$, from equations (A) and (B).

From equation (3), this means that $\vec{v}_{P_1} = \vec{v}_{P_2}$

From equations (1) and (2),

the board velocity is:

$$\vec{v}_{\text{board}} = w_1 R_1 (1 + \cos \theta) \hat{i} - w_1 R_1 \sin \theta \hat{j}$$

and $w_1 R_1 = w_2 R_2$

This is the (board velocity - since P_1 and P_2 are points on the board which do not move relative to the board)

Since $\omega_b = 0$, the board velocity given previously is valid for every point on the board, including its center of mass. The board only experiences translational motion, and no rotational motion.

$$\text{Now, } |\vec{v}_{\text{board}}|^2 = 2(\omega_1 R_1)^2 (1 + \cos\theta) \quad (4)$$

The velocity of the center of mass of the smaller cylinder is:

$$\vec{v}_{\text{cm}_1} = \omega_1 R_1 \hat{i}$$

$$\text{so that, } |\vec{v}_{\text{cm}_1}|^2 = (\omega_1 R_1)^2 \quad (5)$$

The velocity of the center of mass of the larger cylinder is:

$$\vec{v}_{\text{cm}_2} = \omega_2 R_2 \hat{i}$$

$$\text{so that, } |\vec{v}_{\text{cm}_2}|^2 = (\omega_2 R_2)^2 = (\omega_1 R_1)^2 \quad (6)$$

The angular velocity of the smaller cylinder is ω_1 .

The angular velocity of the larger cylinder is: $\omega_2 = \frac{\omega_1 R_1}{R_2}$ (since $\omega_1 R_1 = \omega_2 R_2$)

Since $\omega_1 R_1 = \omega_2 R_2$, $\vec{v}_{\text{cm}_1} = \vec{v}_{\text{cm}_2}$, and as a result, the distance between the center of mass of both cylinders stays constant, at 35 cm.

From the geometry shown on the diagram on the first page (proof not shown),

$$\tan\left(\frac{\theta}{2}\right) = \frac{7-5}{35}, \quad \theta = 6.54^\circ, \quad \theta = \text{constant throughout motion}$$

The cylinders moving a distance of 30 cm means that their center of mass moves 30 cm. Since the cylinders roll on a horizontal surface, their center of mass does not change in elevation, and they don't need to be considered for grav. pot. energy

Now, $\vec{v}_{cm1} = \vec{v}_{cm2}$, so rolling distance of center of mass = $\int_0^T \omega, R, dt = 0.30 \text{ m}$

The board velocity in the downward (negative y) direction is $\omega, R, \sin\theta$

where T is the time it takes for the cylinders to roll 30 cm

So the change in height of the center of mass of board is:

$$\Delta H = - \int_0^T \omega, R, \sin\theta dt$$

$$\Rightarrow \Delta H = -\sin\theta \int_0^T \omega, R, dt = -0.30 \sin\theta \text{ (meters)}$$

Lastly, apply conservation of energy equation:

$$T_1 + V_1 = T_2 + V_2$$

$$T_1 = 0 \text{ (system starts from rest)}$$

$$V_1 = 0 \text{ (datum for center of mass of board chosen at the location of its mass center)}$$

kinetic energy of smaller cylinder

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$$T_2 = \frac{1}{2} m_{c1} |\vec{v}_{cm1}|^2 + \frac{1}{2} I_{G1} \omega_1^2$$

$$+ \frac{1}{2} m_{c2} |\vec{v}_{cm2}|^2 + \frac{1}{2} I_{G2} \omega_2^2 + \frac{1}{2} m_b |\vec{v}_{board}|^2$$

kinetic energy of larger cylinder

kinetic energy of board

$$V_2 = m_b g (\Delta H)$$

Substitute above quantities into conservation of energy equation, and also substitute $m_{c1} = 5 \text{ kg}$, $|\vec{v}_{cm1}|^2 = (\omega_1 R_1)^2 = \omega_1^2 (0.05)^2$, $I_{G1} = \frac{1}{2} m_{c1} R_1^2 = \frac{1}{2} (5)(0.05)^2$, $m_{c2} = 10 \text{ kg}$,

$$|\vec{v}_{cm2}|^2 = (\omega_1 R_1)^2 = \omega_1^2 (0.05)^2, I_{G2} = \frac{1}{2} m_{c2} R_2^2 = \frac{1}{2} (10)(0.07)^2,$$

$$\omega_2 = \omega_1 (R_1 / R_2) = \omega_1 (5/7),$$

$$m_b = 13 \text{ kg}, |\vec{v}_{board}|^2 = 2 \omega_1^2 (0.05)^2 (1 + \cos 6.54^\circ),$$

$$\Delta H = -0.3 \sin 6.54^\circ = -0.03417 \text{ m}$$

The result is:

$$0 = 0.00625 \omega_1^2 + 0.003125 \omega_1^2 + 0.0125 \omega_1^2$$

$$+ 0.00625 \omega_1^2 + 0.06479 \omega_1^2 - 4.353$$

Solve for $\omega_1 = 6.84 \text{ rad/s}$

Then, $\vec{v}_{board} = 0.68 \hat{i} - 0.039 \hat{j} \text{ m/s}$ (answer)