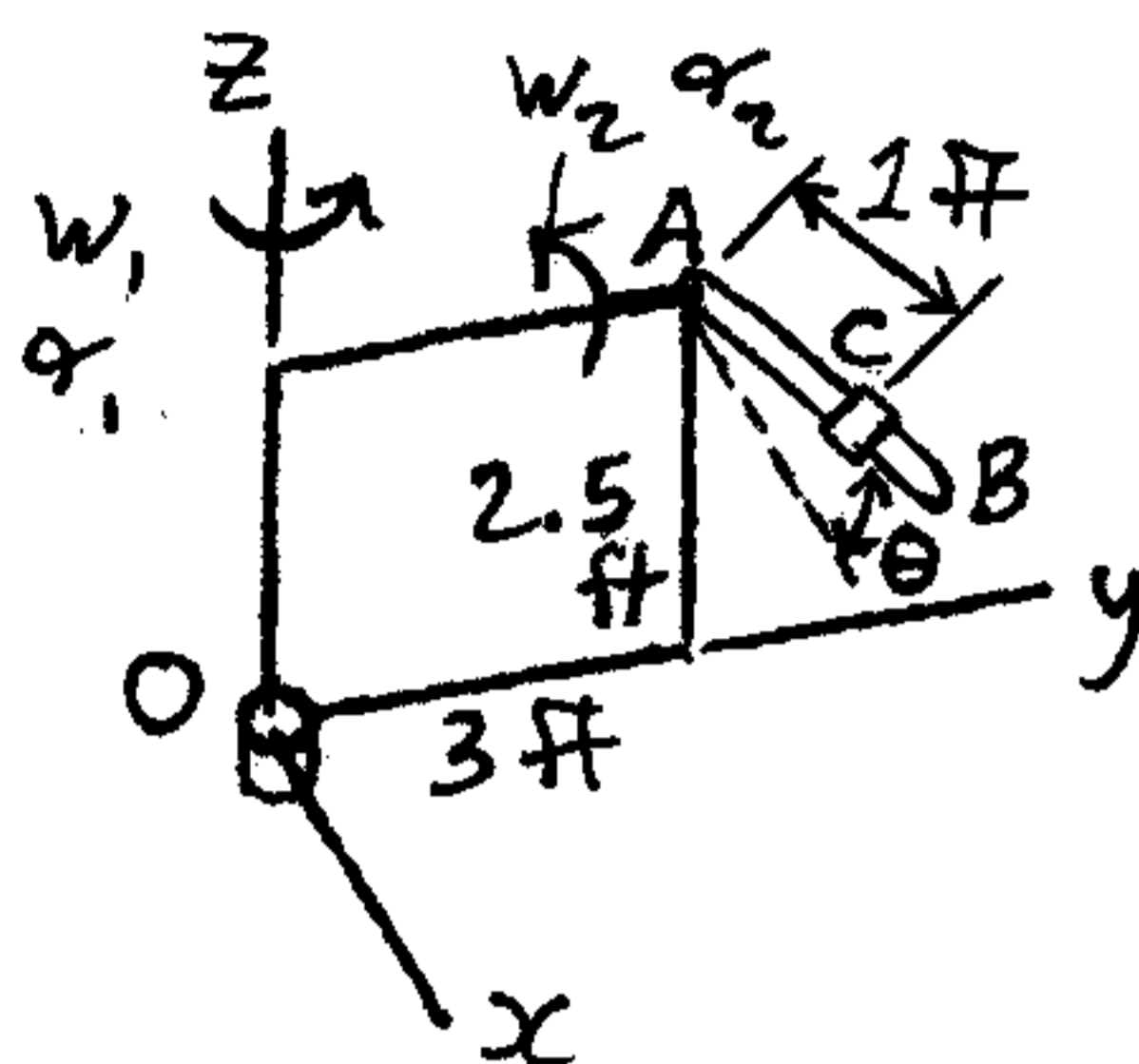


This is a 3D general motion problem (engineering mechanics).



A rectangular plate is rotating about the z -axis with an angular velocity of $w_1 = 0.8 \text{ rad/s}$, and an angular acceleration of $\alpha_1 = 1.2 \text{ rad/s}^2$, as shown. At the same instant, a rod AB that is connected to the plate, is rotating relative to the plate at an angular velocity of $w_2 = 2 \text{ rad/s}$ and an angular acceleration of $\alpha_2 = 3 \text{ rad/s}^2$. If $\theta = 30^\circ$, the plate side lengths are 3 ft and 2.5 ft , the distance between the collar C and point A is 1 ft , and C slides towards A with a velocity of 1.5 ft/s and a deceleration of -2.1 ft/s^2 , both measured relative to the rod, what is the velocity and acceleration of the collar C at the instant shown?

Solution:

$$\vec{V}_C = \vec{V}_A + \vec{\omega} \times \vec{r}_{C/A} + (\vec{V}_{C/A})_{rel} \quad , \text{ where } \vec{\omega} \text{ is the angular velocity of the rod AB.}$$

$$\vec{V}_A = \vec{V}_O + \vec{\omega}_1 \times \vec{r}_{A/O}$$

$$\vec{r}_{C/A} = 1 \cos \theta \hat{i} + 1 \sin \theta \hat{k}$$

$$(\vec{V}_{C/A})_{rel} = -1.5 \cos \theta \hat{i} - 1.5 \sin \theta \hat{k}$$

$$\vec{\omega}_1 = \omega_1 \hat{k}$$

$$\vec{r}_{A/O} = 3 \hat{j} + 2.5 \hat{k}$$

$$\vec{\omega} = -\omega_2 \hat{j} + \omega_1 \hat{k}$$

Substitute:

$$\vec{V}_C = \vec{\omega}_1 \times \vec{r}_{A/O} + \vec{\omega} \times \vec{r}_{C/A} + (\vec{V}_{C/A})_{rel}$$

Now,

$$\vec{V}_C = (\omega_1 \hat{k}) \times (3 \hat{j} + 2.5 \hat{k}) + (-\omega_2 \hat{j} + \omega_1 \hat{k}) \times (\cos \theta \hat{i} + \sin \theta \hat{k}) - 1.5 \cos \theta \hat{i} - 1.5 \sin \theta \hat{k}$$

$$\vec{V}_C = (0.8 \hat{k}) \times (3 \hat{j} + 2.5 \hat{k}) + (-2 \hat{j} + 0.8 \hat{k}) \times (\cos 30^\circ \hat{i} + \sin 30^\circ \hat{k}) - 1.5 \cos 30^\circ \hat{i} - 1.5 \sin 30^\circ \hat{k}$$

$$\vec{V}_C = -4.70 \hat{i} + 0.6928 \hat{j} + 0.9821 \hat{k} \quad (\text{answer})$$

ft/s

Next,

$$\vec{a}_C = \vec{a}_A + \vec{\alpha} \times \vec{r}_{C/A} + \vec{\omega} \times (\vec{\omega} \times \vec{r}_{C/A}) + 2\vec{\omega} \times (\vec{v}_{C/A})_{rel} + (\vec{a}_{C/A})_{rel}$$

$$\vec{a}_A = \vec{a}_O + \vec{\alpha}_1 \times \vec{r}_{A/O} + \vec{\omega}_1 \times (\vec{\omega}_1 \times \vec{r}_{A/O}) + (\vec{a}_{C/A})_{rel}$$

where $\vec{\alpha}$ is the angular acceleration of the rod AB

$$(\vec{a}_{C/A})_{rel} = 2.1 \cos \theta \hat{i} + 2.1 \sin \theta \hat{k}$$

$$\vec{\alpha}_1 = \alpha_1 \hat{k}$$

substitute: $\vec{\alpha} = -\alpha_2 \hat{j} + \alpha_1 \hat{k} + \omega_1 \omega_2 \hat{i}$

$$\vec{a}_C = \vec{\alpha}_1 \times \vec{r}_{A/O} + \vec{\omega}_1 \times (\vec{\omega}_1 \times \vec{r}_{A/O}) + \vec{\alpha} \times \vec{r}_{C/A} + \vec{\omega} \times (\vec{\omega} \times \vec{r}_{C/A}) + 2\vec{\omega} \times (\vec{v}_{C/A})_{rel} + (\vec{a}_{C/A})_{rel}$$

$$\vec{a}_C = (1.2 \hat{k}) \times (3 \hat{j} + 2.5 \hat{k}) + (0.8 \hat{k}) \times [(0.8 \hat{k}) \times (3 \hat{j} + 2.5 \hat{k})] + (0.8)(2) \hat{i} - 3 \hat{j} + 1.2 \hat{k} \times (\cos 30^\circ \hat{i} + \sin 30^\circ \hat{k}) + (-2 \hat{j} + 0.8 \hat{k}) \times [(-2 \hat{j} + 0.8 \hat{k}) \times (\cos 30^\circ \hat{i} + \sin 30^\circ \hat{k})] + 2(-2 \hat{j} + 0.8 \hat{k}) \times (-1.5 \cos 30^\circ \hat{i} - 1.5 \sin 30^\circ \hat{k}) + 2.1 \cos 30^\circ \hat{i} + 2.1 \sin 30^\circ \hat{k}$$

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$$\vec{a}_c = -4.30\hat{i} - 4.559\hat{j} - 3.548\hat{k} \text{ ft/s}^2 \text{ (answer)}$$